

# PARALLEL FAST GAUSS TRANSFORM

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# PROBLEM STATEMENT

Fast algorithms to compute discrete sums of the form:

$$F(x_j) = \sum_{k=1}^N G_\delta(\|x_j - y_k\|)f(y_k) \quad \text{at} \quad \{x_j \mid j = 1, \dots, N\}$$

$x \rightarrow$  targets

$G_\delta$  is a *Gaussian-type* kernel

$y \rightarrow$  sources

space-limited

$f \rightarrow$  source strength

band-limited

$x, y \in [0, 1]^d$

e.g.,  $G_\delta = \|x\|^2 e^{-\frac{\|x\|^2}{\delta}}$

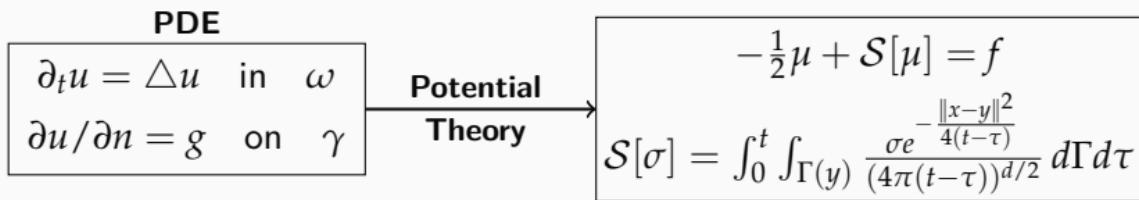
Näive algorithm is  $\mathcal{O}(N^2)$

# MOTIVATION

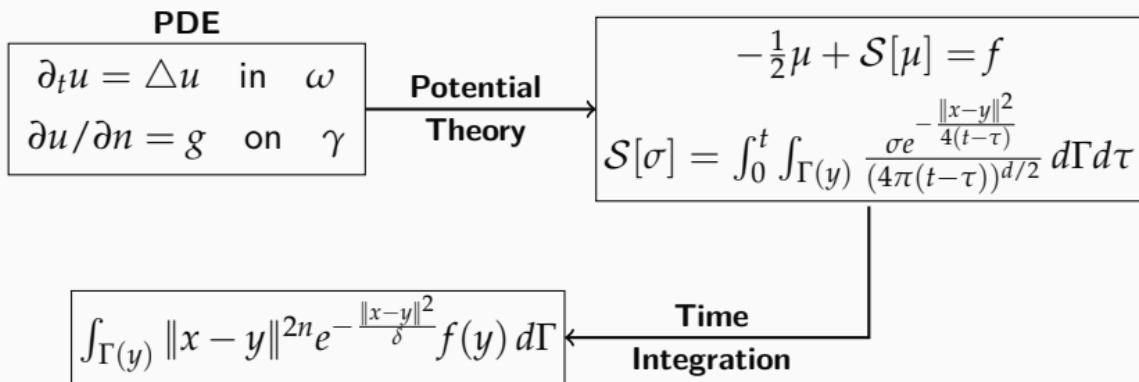
**PDE**

$$\begin{aligned}\partial_t u &= \Delta u \quad \text{in} \quad \omega \\ \partial u / \partial n &= g \quad \text{on} \quad \gamma\end{aligned}$$

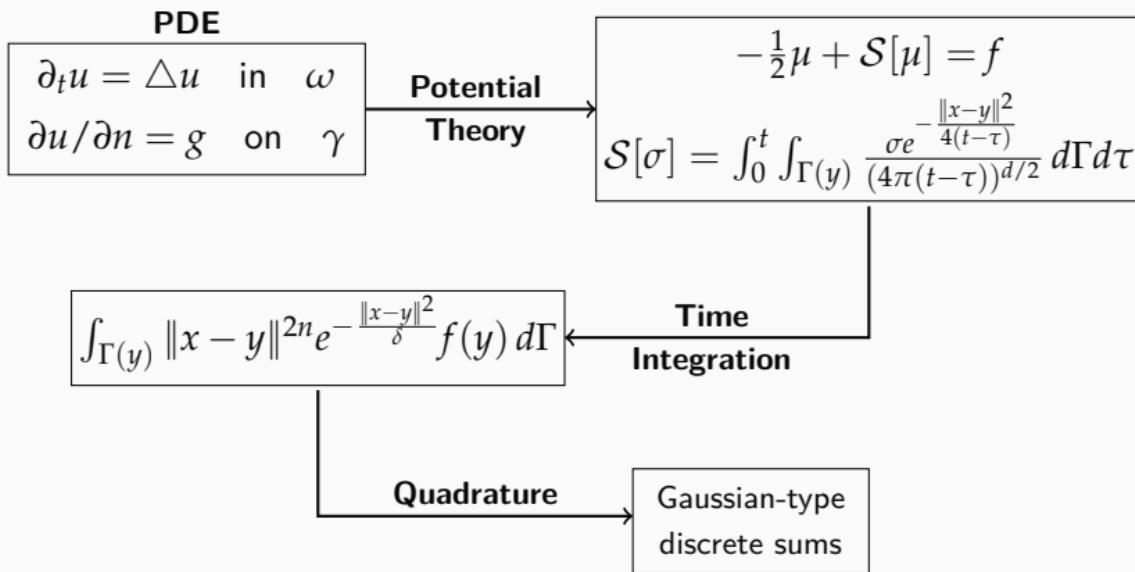
# MOTIVATION



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PDE	Kernels
Diffusion	$\partial_t u = \Delta u$
Reaction-diffusion	$\partial_t u = \Delta u + u^2$
Unsteady Stokes	$\partial_t \mathbf{u} = -\nabla P + \Delta \mathbf{u}$
Navier-Stokes	$\partial_t \mathbf{u} + \mathbf{u} \cdot \nabla \mathbf{u} = -\nabla P + \Delta \mathbf{u}$

# RELATED WORK

## Sequential

Greengard & Strain, 1991	FGT - Hermite expansions
Strain, 1991	variable scales
Greengard & Sun, 1998	Plane wave expansions
Sun & Bao, 2002	Kronecker-product rep.
Yang et al., 2003	high-dimensional FGT for KDEs
Spivak et al., 2010	Generalized FGT

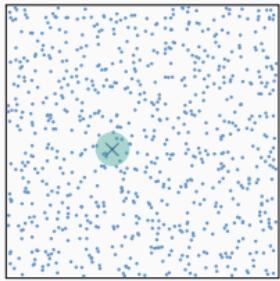
## Parallel

Yamamoto, 2006	1D, $n_p \leq 16, N = \mathcal{O}(100)$
Yokota et al., 2009	RBFs, not optimal if Gaussian spread is large

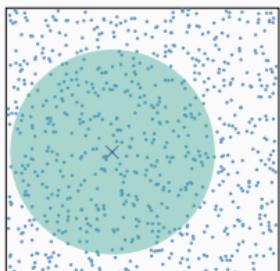
# OVERVIEW OF FGT

# TRUNCATION

$$e^{-\frac{\|x-y\|^2}{\delta}}$$



small  $\delta$



large  $\delta$

$\delta$  controls the decay of the kernel

If  $\delta$  is small,

for each  $x$

$$F(x) = \sum_{y \in \mathcal{I}[x]} G_\delta(\|x - y\|)f(y)$$

end

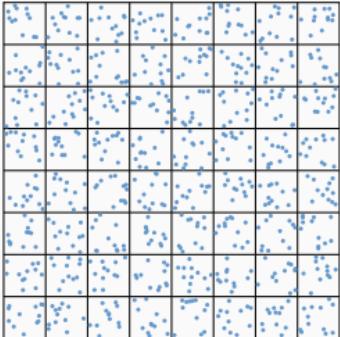
Sequential complexity:  $\mathcal{O}(p^d N)$

Embarassingly parallel

## EXPANSION

$$e^{-\|x-y\|^2/\delta} \approx \sum_{|k| \leq p} \hat{G}(k) e^{i\lambda k \cdot (x-y)}$$

$$\hat{G}(k) = \left( \frac{L}{2p\sqrt{\pi}} \right)^3 e^{-\frac{\lambda^2 |k|^2 \delta}{4}}, \quad \lambda = \frac{L}{p\sqrt{\delta}}$$



Partition the domain into uniform boxes of size  $\sqrt{\delta}$

A fixed number ( $K^d$ ) of neighboring boxes influence targets in a particular box

# EXPANSION

**(S2W)** Sources to Wave expansions  $\mathcal{O}(p^d N)$

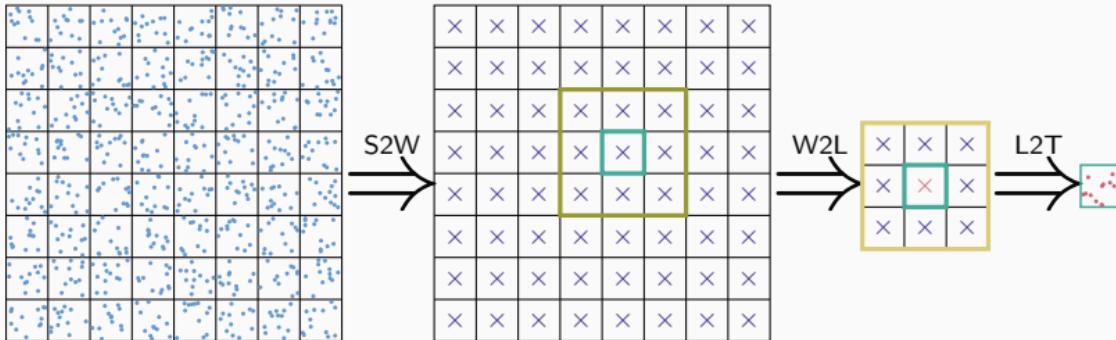
$$w_k = \sum_{y \in B} f(y) e^{i \lambda k \cdot (c^B - y)}$$

**(W2L)** Wave to Local expansions  $\mathcal{O}(K^d p^d N_{\text{box}})$

$$v_k+ = w_k e^{i \lambda k \cdot (c^D - c^B)}$$

**(L2T)** Local expansion to Targets  $\mathcal{O}(p^d N)$

$$F(x) = \sum_{|k| \leq p} \hat{G}(k) v_k e^{i \lambda k \cdot (x - c^D)}$$

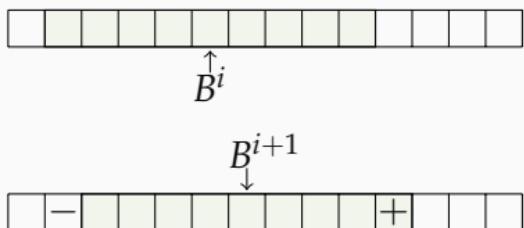


# FGT: TRANSLATION

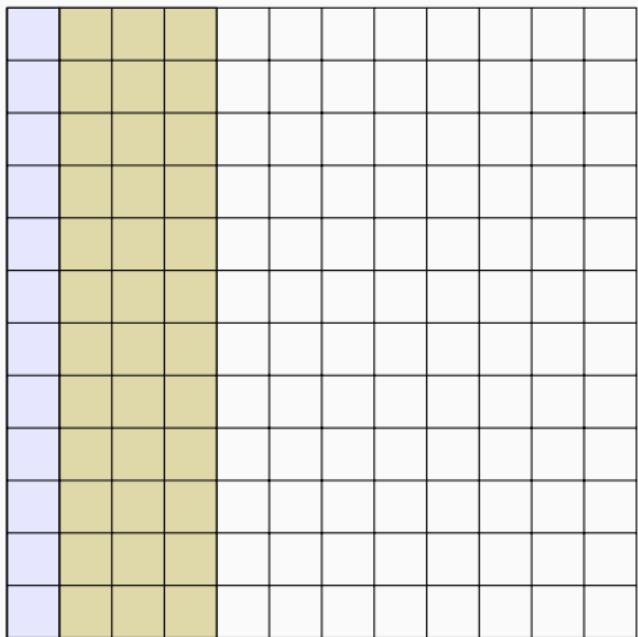
Reduces per box translation cost

$$K^3 p^3 \rightarrow 9p^3$$

( $K = 13$  for  $\epsilon = 10^{-12}$ )



$$v^{j+1} = \beta v^j - \alpha^l w^l + \alpha^r w^r$$

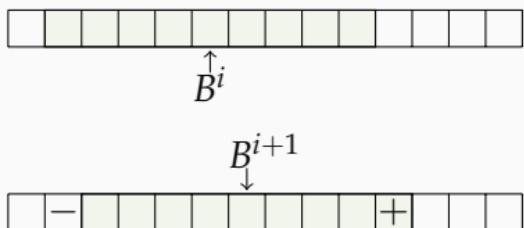


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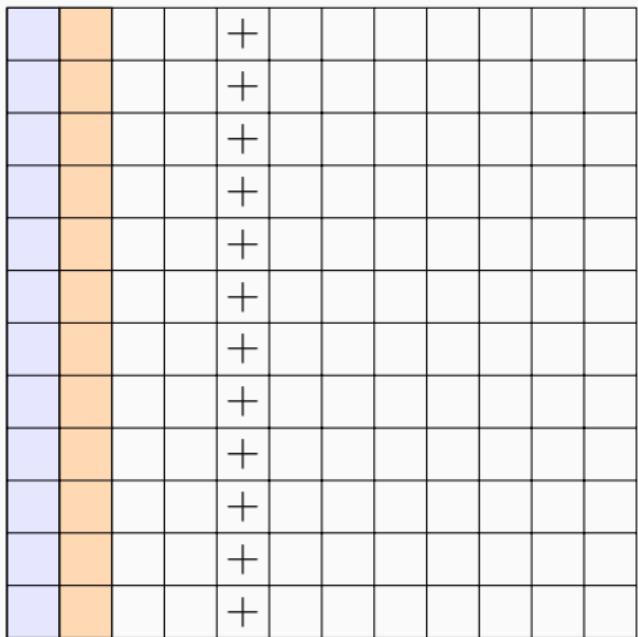
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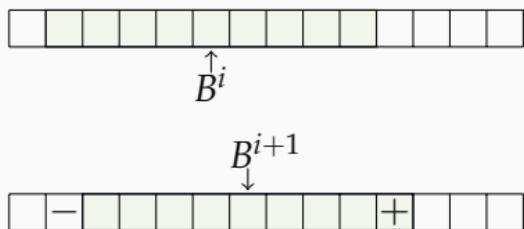


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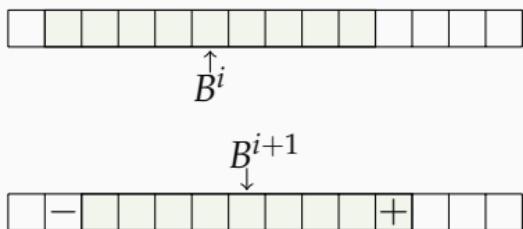
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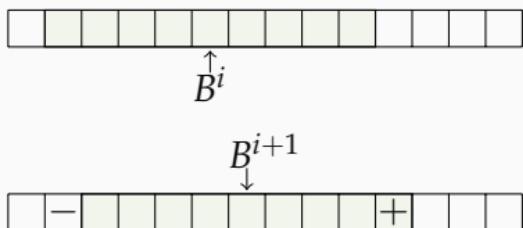
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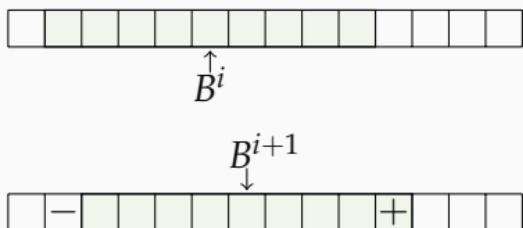
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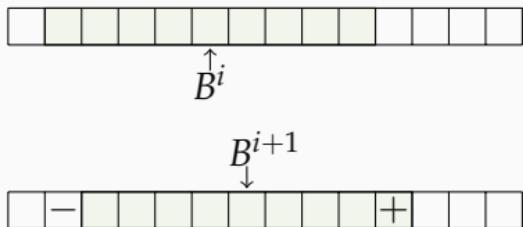
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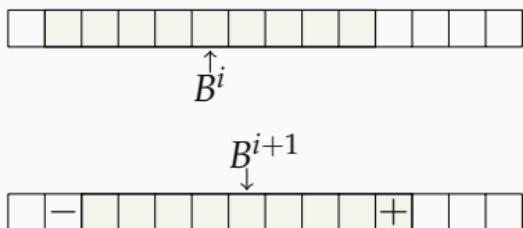
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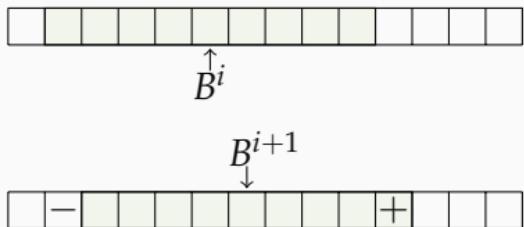
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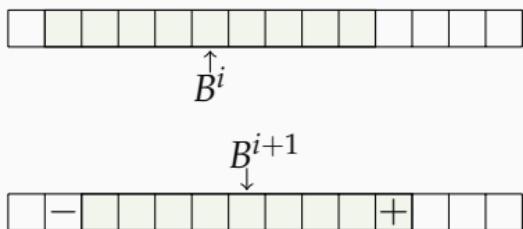
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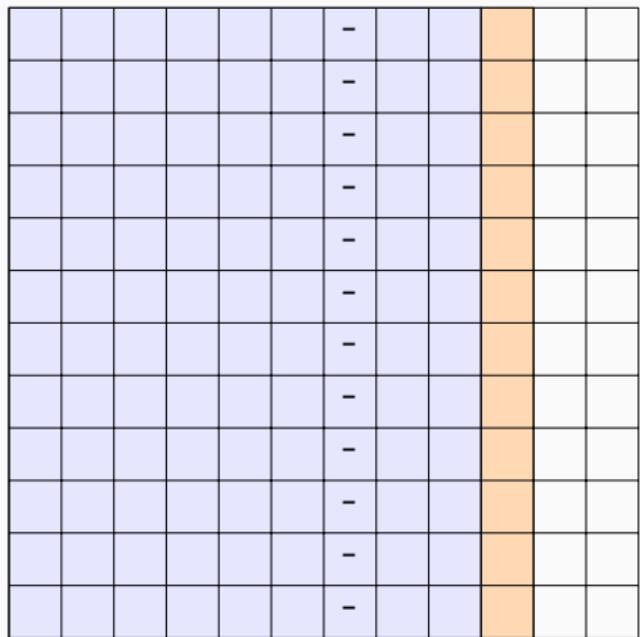
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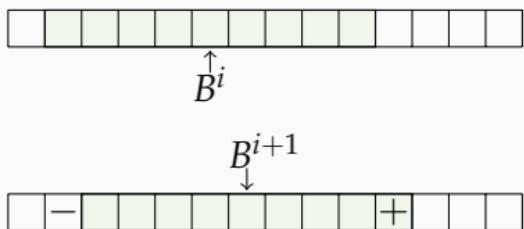


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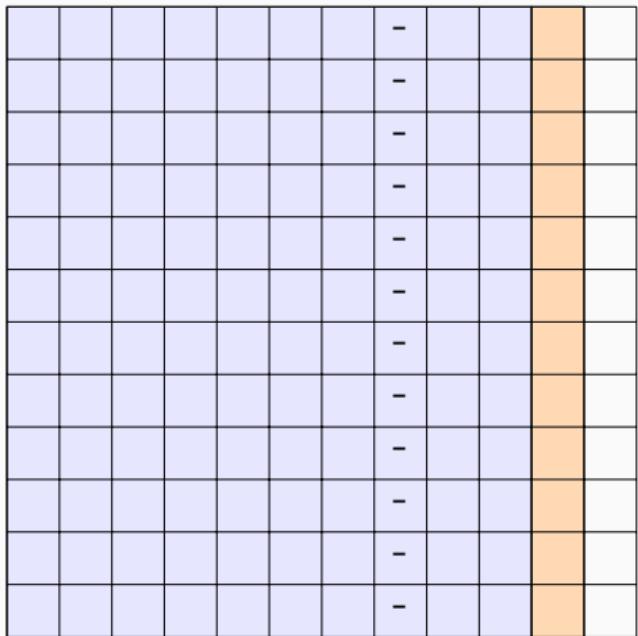
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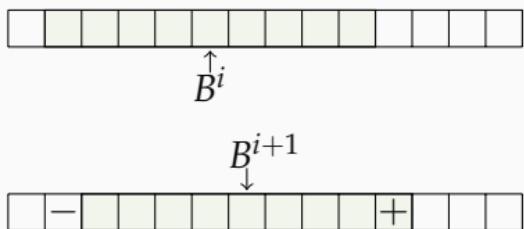


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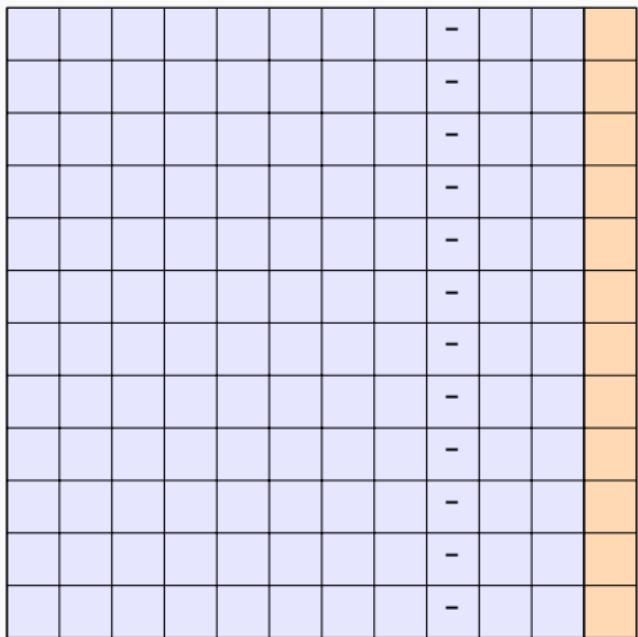
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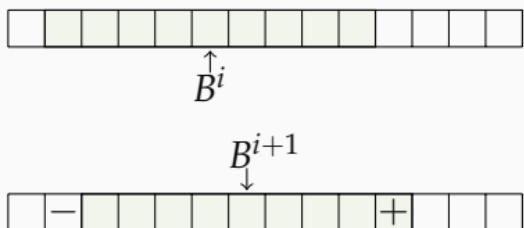


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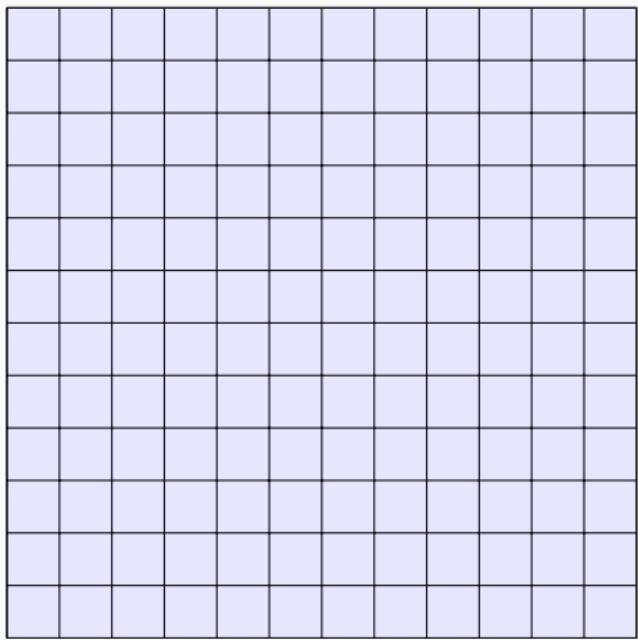
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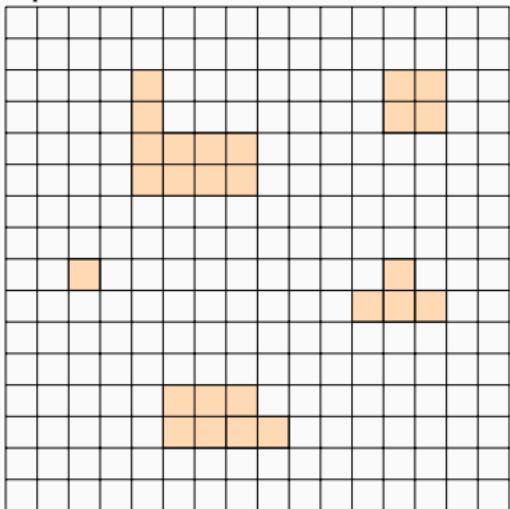


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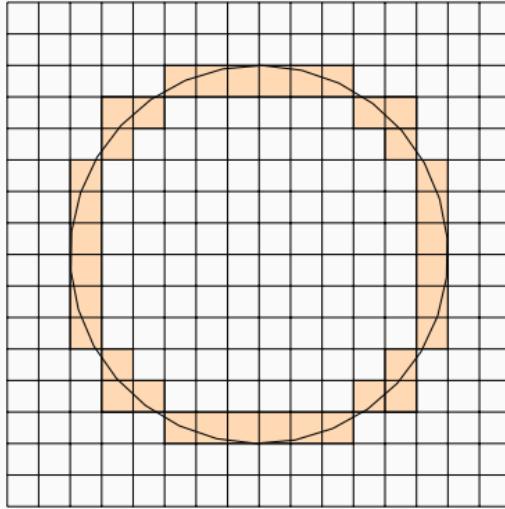


# GLOBAL SWEEP: DRAWBACKS

Sparse Volume distribution



Surface Distribution



Global sweep *fills-in* empty boxes

Higher storage and computational costs

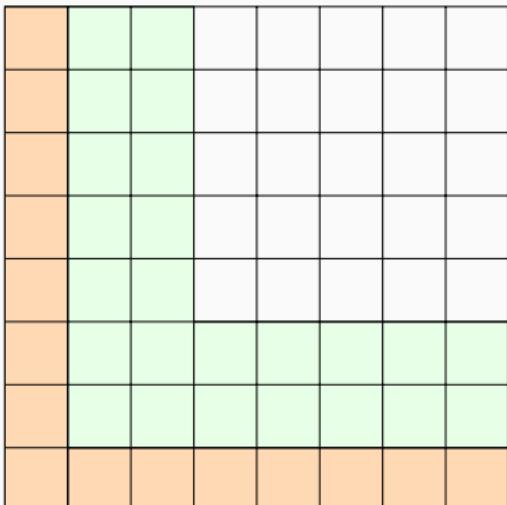
# VOLUME DISTRIBUTIONS: LOCAL SWEEP

## New Stencil

$$v_k^{(i+1,j+1)} = \sum_{\xi} (-1)^{1+d+\mathcal{M}(\xi)} e^{i\lambda k \cdot \xi} v_k^{(i,j)+\xi} + \sum_{\chi} (-1)^{1+d+\mathcal{M}(\chi)} e^{i\lambda k \cdot \chi} w_k^{(i,j)+\chi}.$$

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	$i,j+1$	$i+1,j+1$		
	$i,j$	$i+1,j$		
-				-

Direct translation for first layer



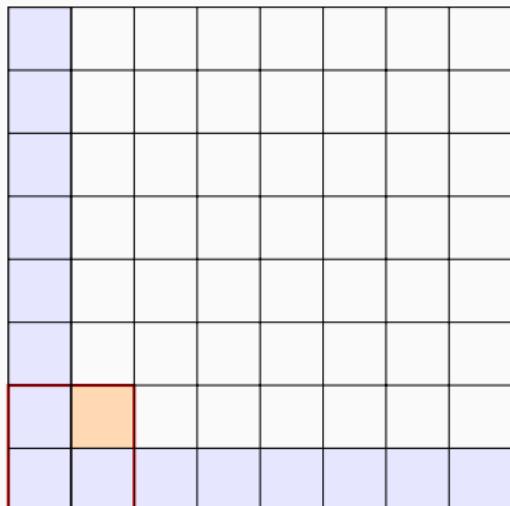
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-			-

Propagate to subsequent layers



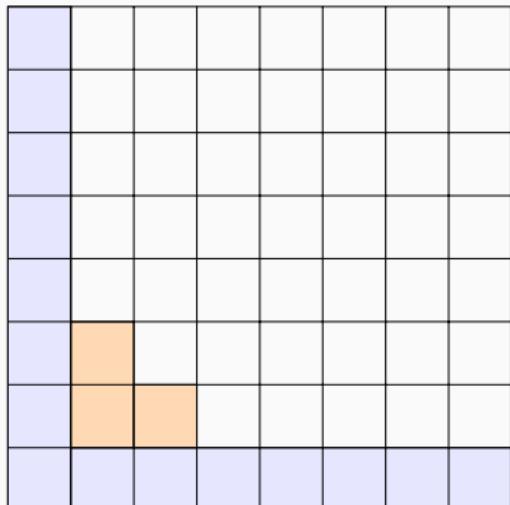
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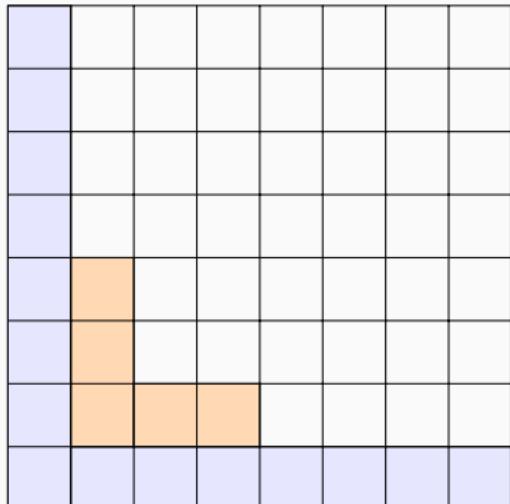
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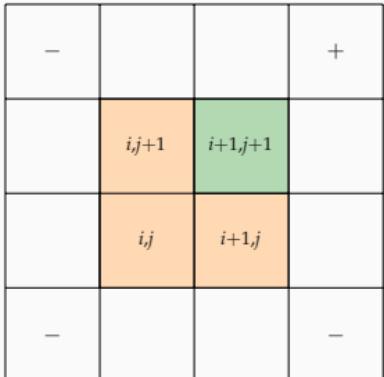
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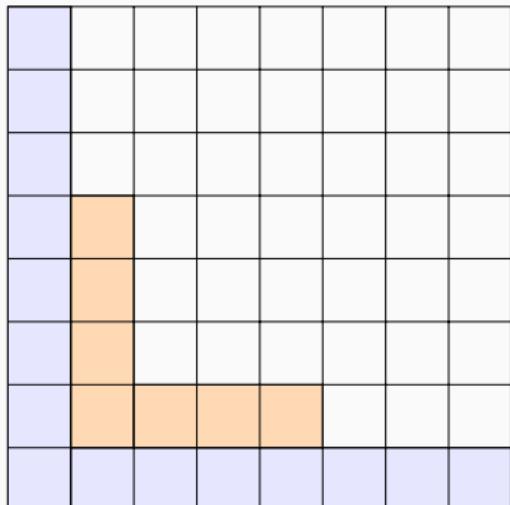
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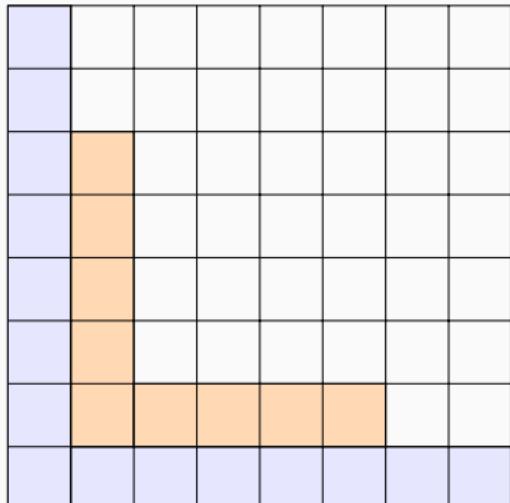
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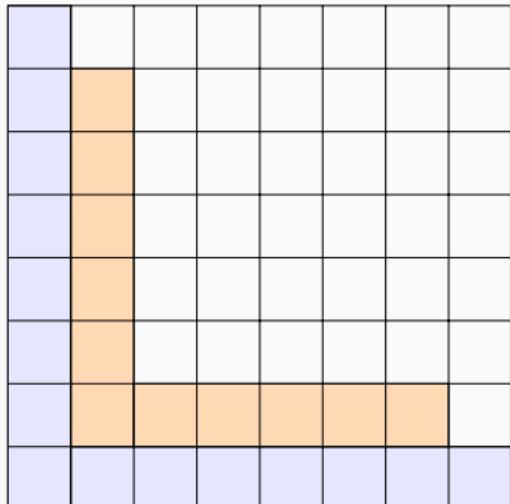
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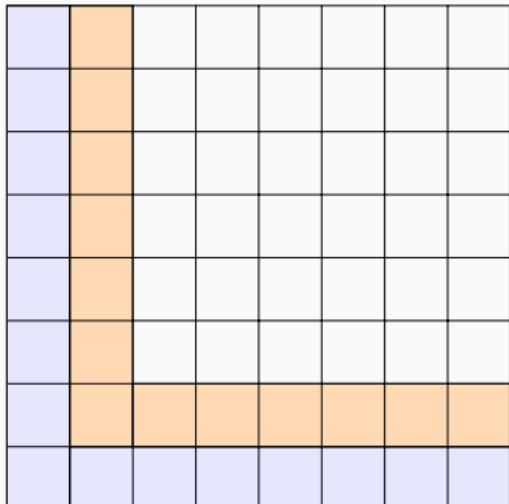
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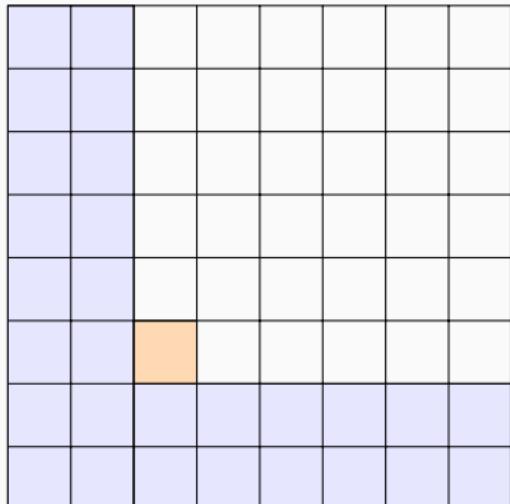
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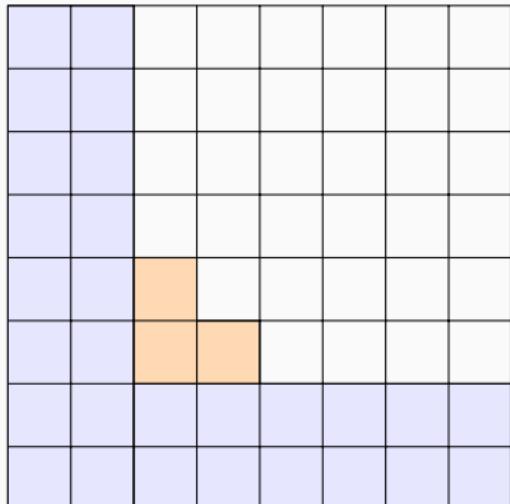
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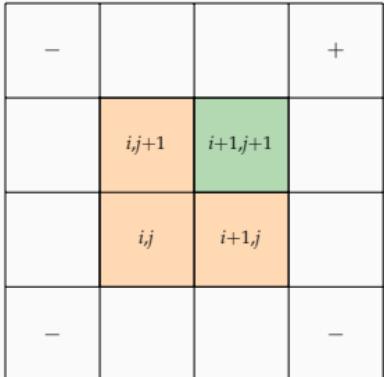
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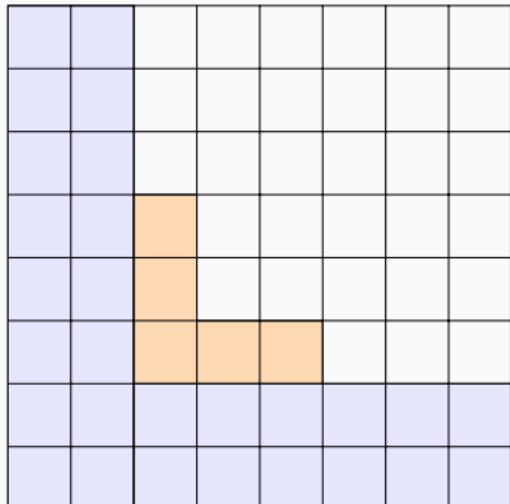
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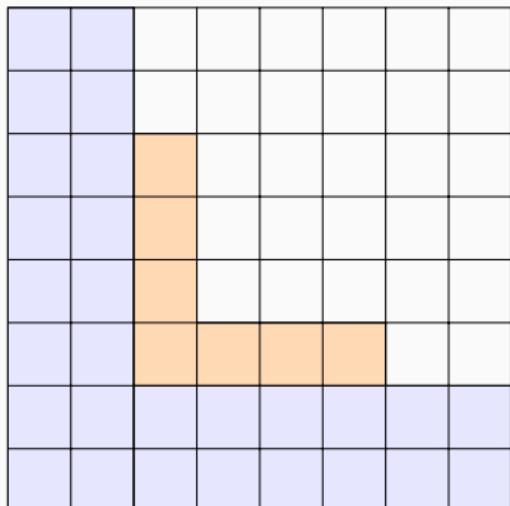
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	$i,j+1$	$i+1,j+1$	
	$i,j$	$i+1,j$	
-			-

Propagate to subsequent layers



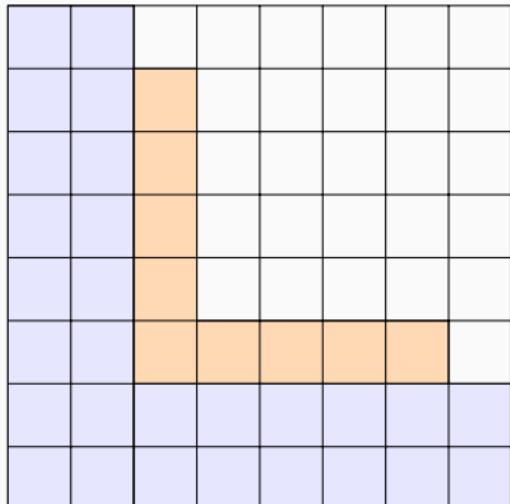
# VOLUME DISTRIBUTIONS: LOCAL SWEEP

## New Stencil

$$v_k^{(i+1,j+1)} = \sum_{\xi} (-1)^{1+d+\mathcal{M}(\xi)} e^{i\lambda k \cdot \xi} v_k^{(i,j)+\xi} + \sum_{\chi} (-1)^{1+d+\mathcal{M}(\chi)} e^{i\lambda k \cdot \chi} w_k^{(i,j)+\chi}.$$

-			+
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-			-

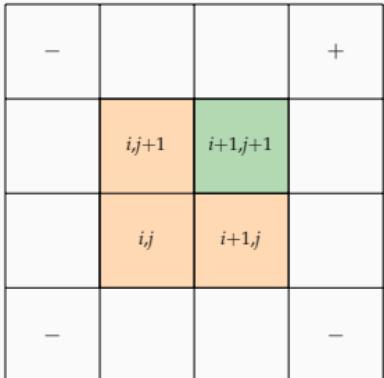
Propagate to subsequent layers



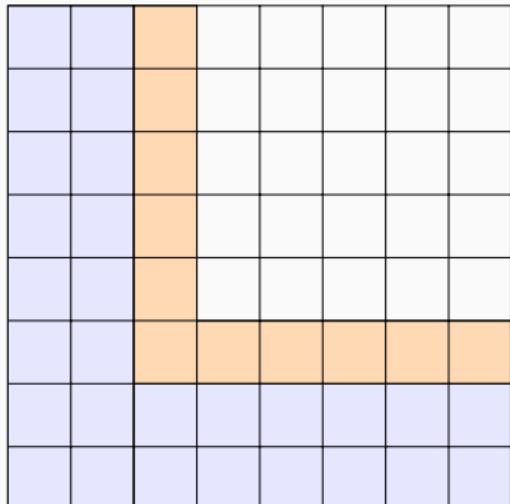
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Propagate to subsequent layers



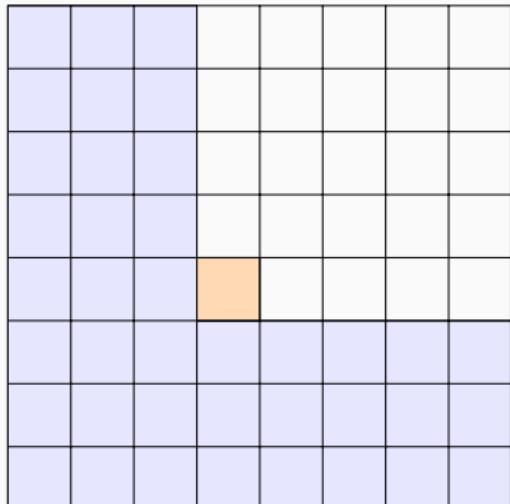
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-			-

Propagate to subsequent layers



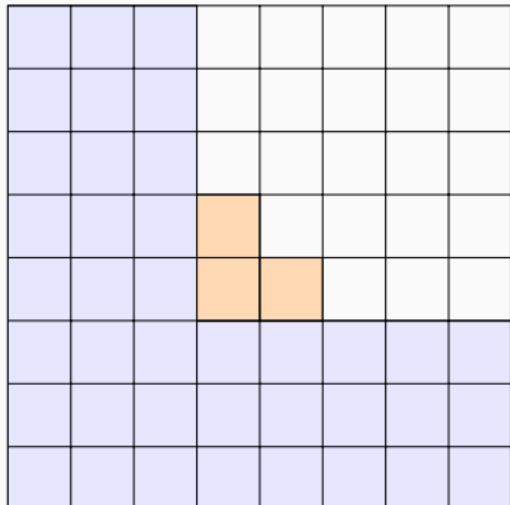
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-			-

Propagate to subsequent layers



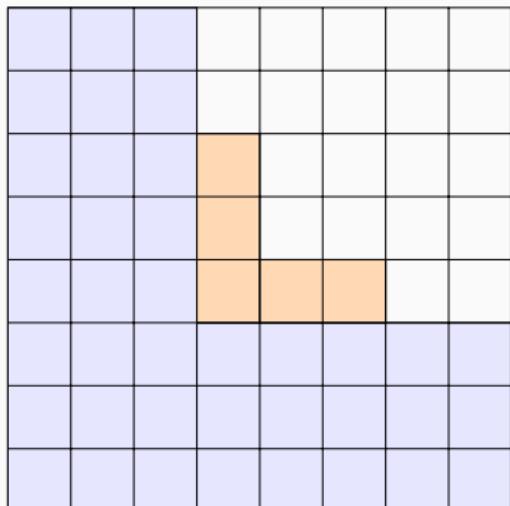
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-			-

Propagate to subsequent layers



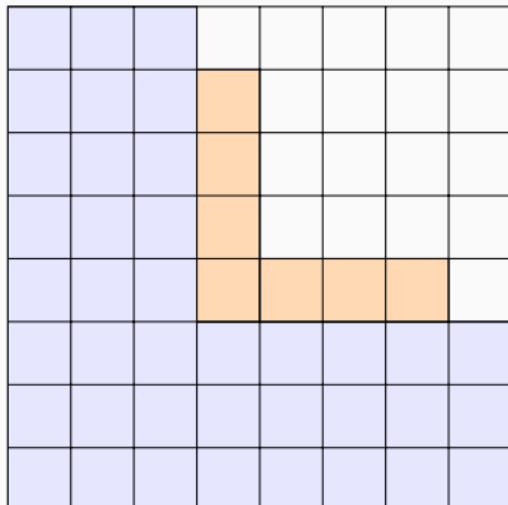
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-			-

Propagate to subsequent layers



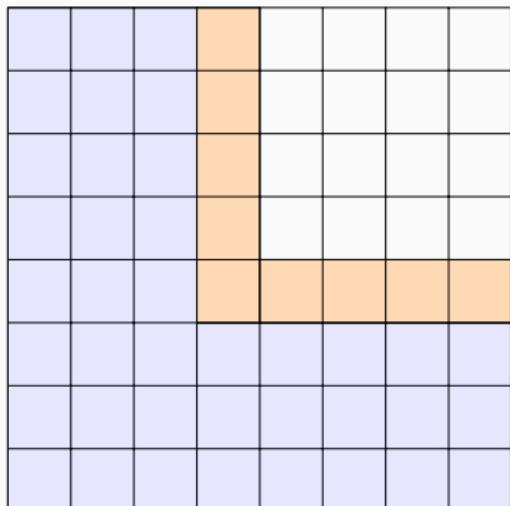
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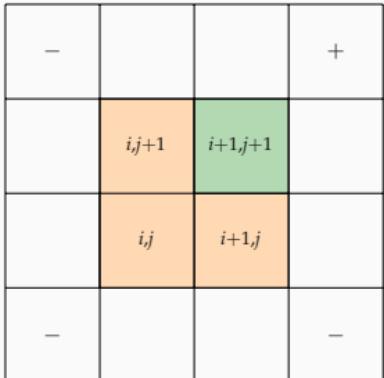
Propagate to subsequent layers



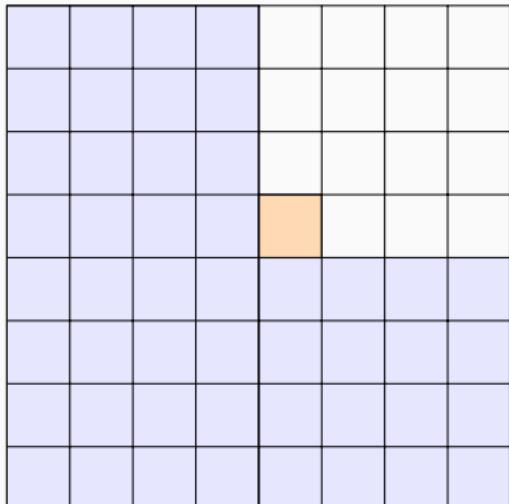
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Propagate to subsequent layers



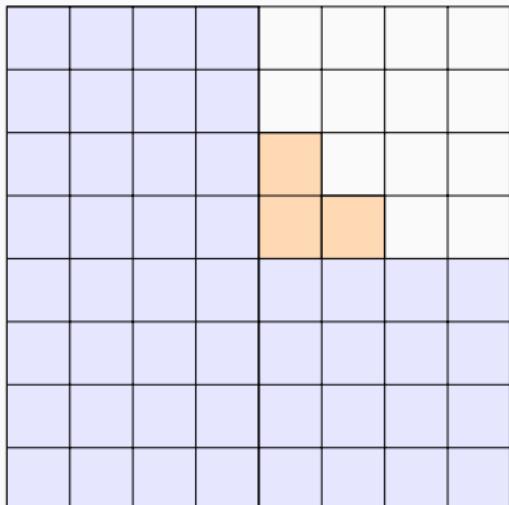
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Propagate to subsequent layers



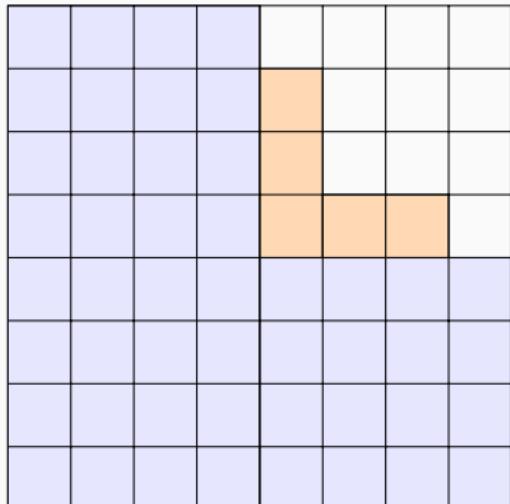
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-			-

Propagate to subsequent layers



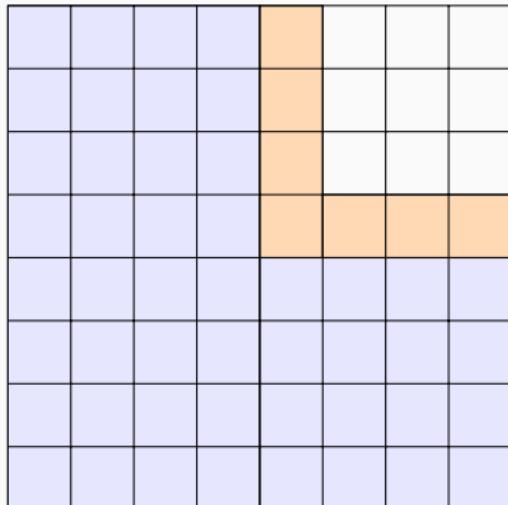
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-			-

Propagate to subsequent layers



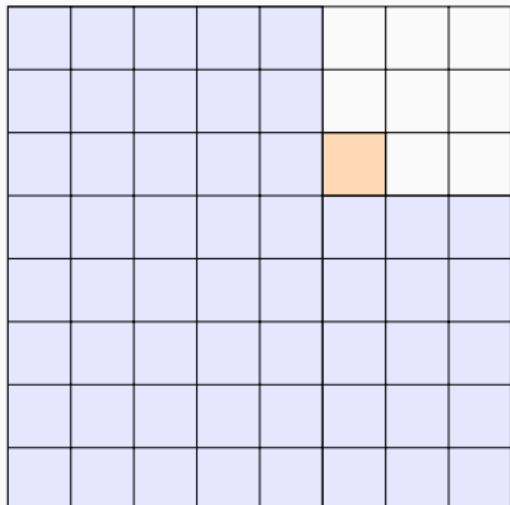
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-			-

Propagate to subsequent layers



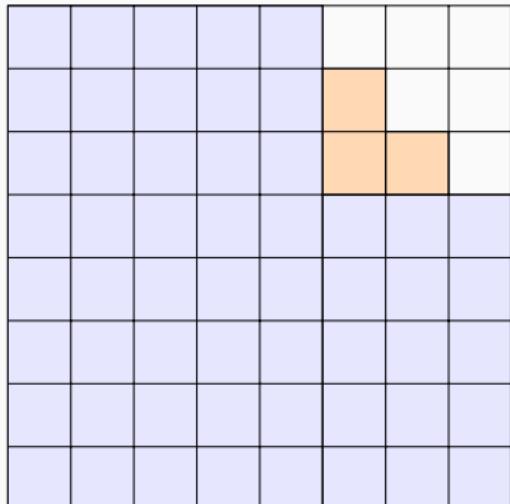
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Propagate to subsequent layers



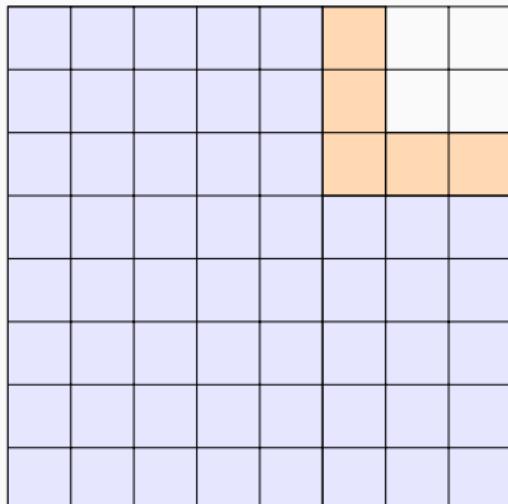
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Propagate to subsequent layers



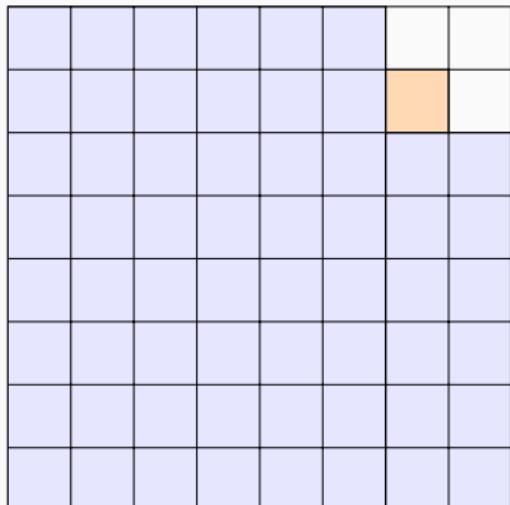
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Propagate to subsequent layers



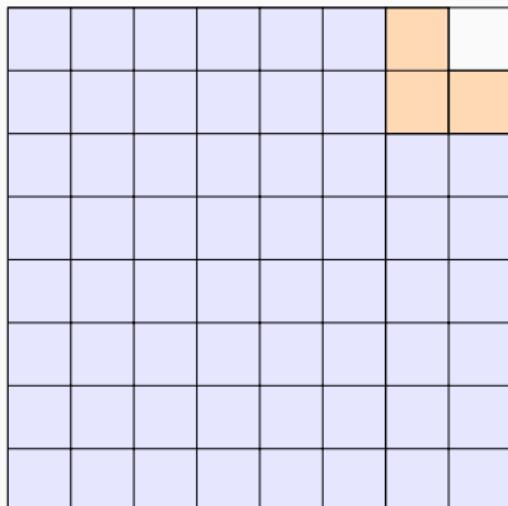
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	$i,j$	$i+1,j$	
-			-

Propagate to subsequent layers



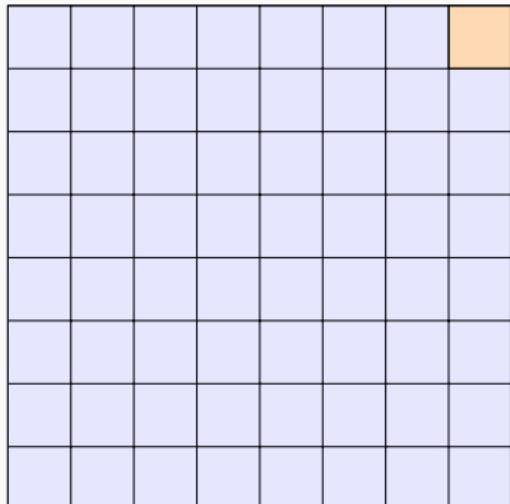
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-			-

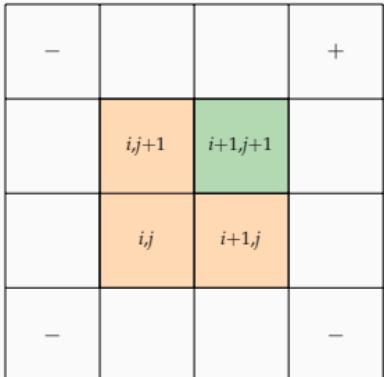
Propagate to subsequent layers



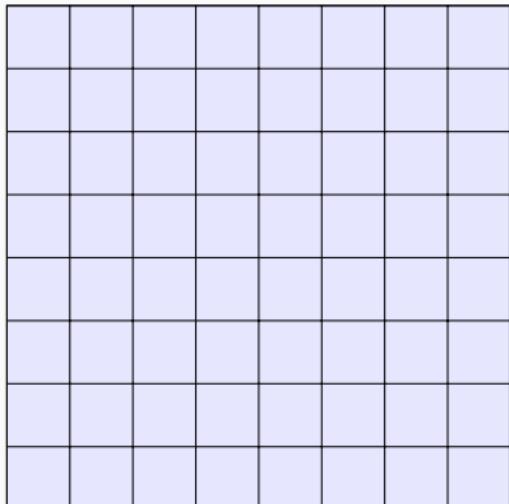
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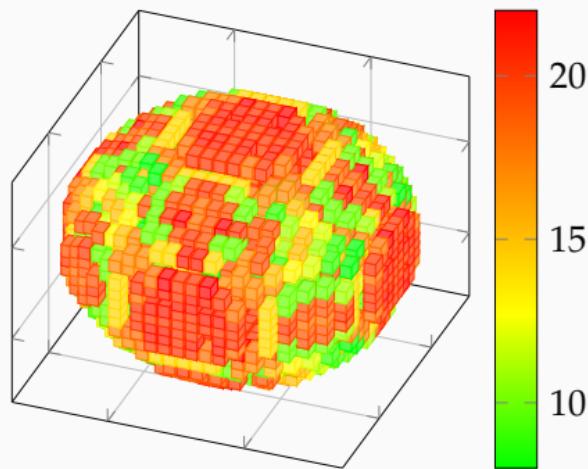


Propagate to subsequent layers



*Find an ordering that maximizes overlap of consecutive interaction lists*

reduce to finding a  
*minimum spanning tree*  
use Kruskal's algorithm  
 $\mathcal{O}(K^2p^3) \rightarrow \mathcal{O}(Kp^3)$



## MST - RESULTS

$$K = 9, \epsilon = 10^{-6}$$

$ B $	direct	MST	ratio
1K	114K	18K	6.3
10K	1M	182K	5.88
100K	9.65M	1.7M	5.68
1M	96.8M	17.1M	5.68

## MST - RESULTS

$$K = 13, \epsilon = 10^{-12}$$

$ B $	direct	MST	ratio
1K	238K	24K	9.65
10K	2.2M	264K	8.48
100K	20.2M	2.5M	8.18
1M	200.6M	24.5M	8.18

# NONUNIFORM DISTRIBUTIONS

# EXPANSION OR TRUNCATION?

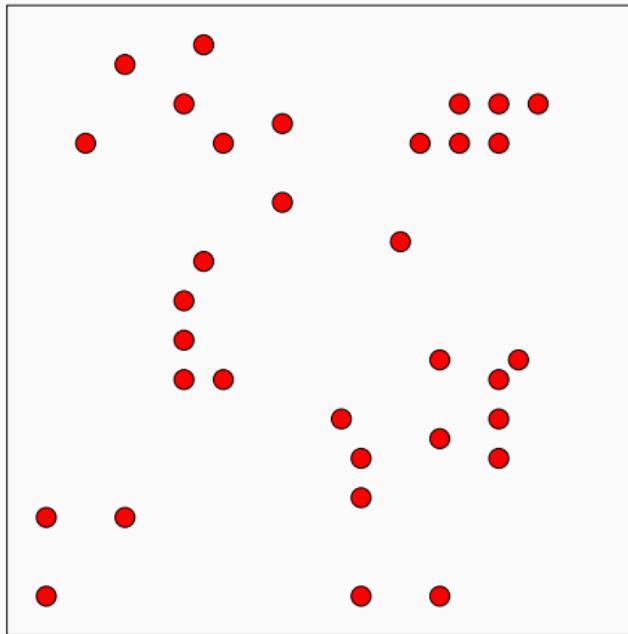
Many sources per FGT box – Expansion

Few sources per FGT box – Truncation

Non-uniform distributions – Hybrid

# TREE CONSTRUCTION

Max. of  $m$  points per leaf

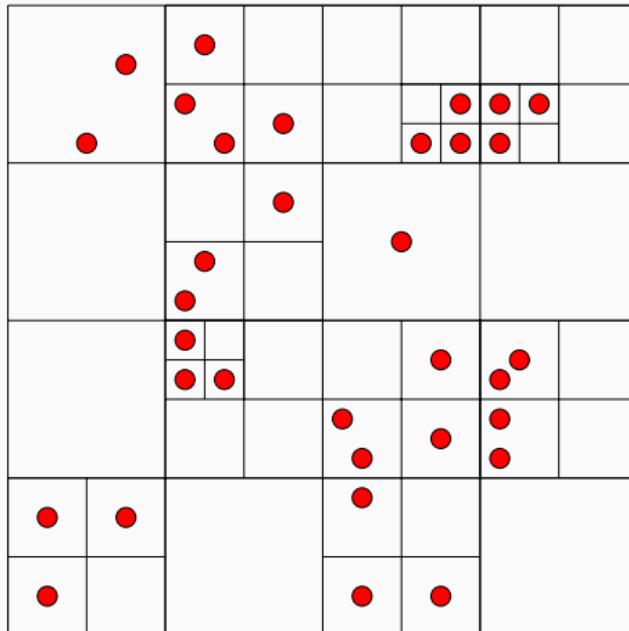


$$m = 2$$

# TREE CONSTRUCTION

Max. of  $m$  points per leaf

Higher point density  $\Rightarrow$   
finer leaves



$$m = 2$$

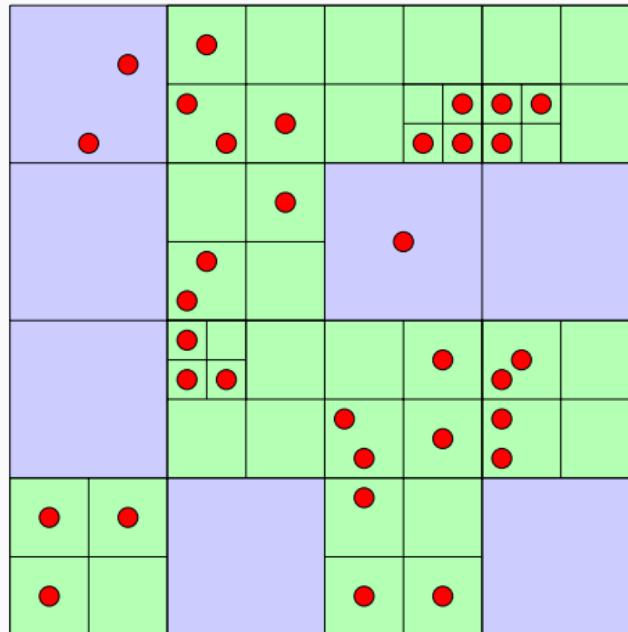
# TREE CONSTRUCTION

Max. of  $m$  points per leaf

Higher point density  $\Rightarrow$   
finer leaves

Large leaves  $\Rightarrow$  Truncation  
(*Direct*)

Small leaves  $\Rightarrow$  Expansion  
(*Expand*)



$$m = 2$$

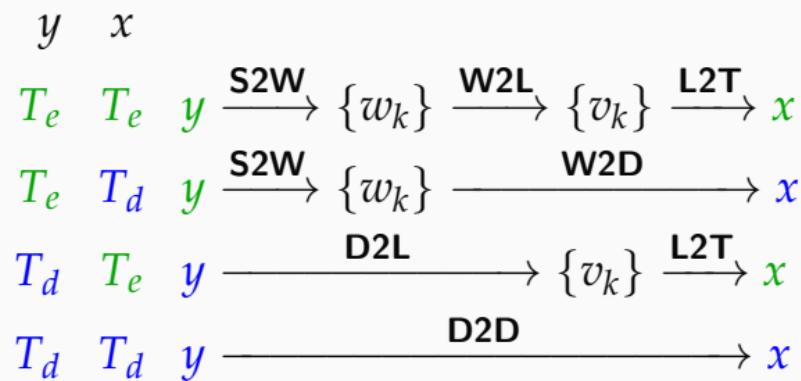
# FLOW OF INFORMATION

Source —  $y$

Target —  $x$

Direct tree —  $T_d$

Expand tree —  $T_e$



# FLOW OF INFORMATION

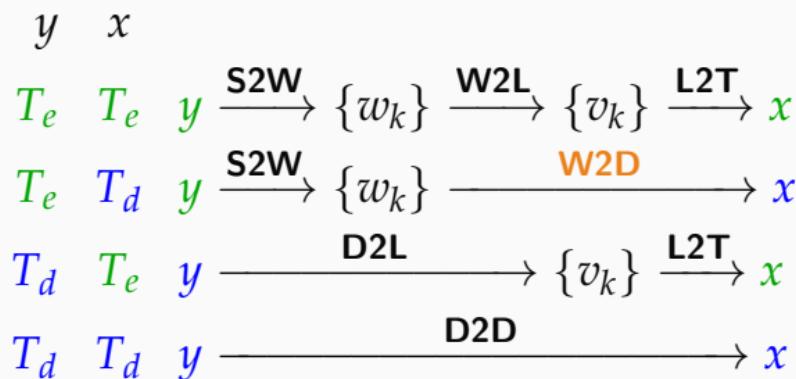
Source —  $y$

Target —  $x$

Direct tree —  $T_d$

Expand tree —  $T_e$

$$F(x) = \sum_{|k| \leq p} \hat{G}(k) w_k e^{i \lambda k \cdot (x - c^B)}$$



# FLOW OF INFORMATION

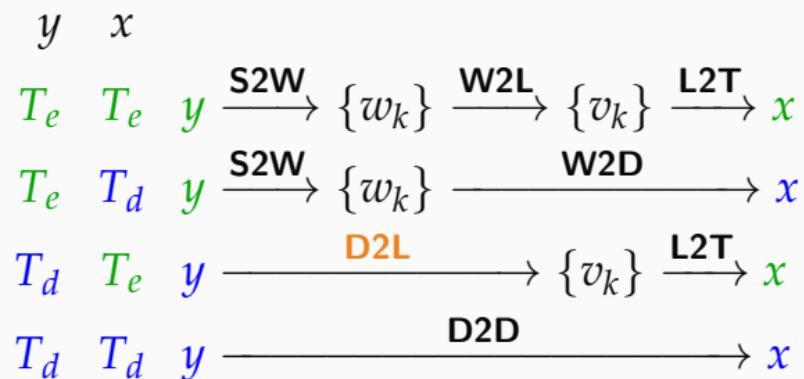
Source —  $y$

Target —  $x$

Direct tree —  $T_d$

$$v_k+ = f(y) e^{i \lambda k \cdot (c^D - y)}$$

Expand tree —  $T_e$



# FLOW OF INFORMATION

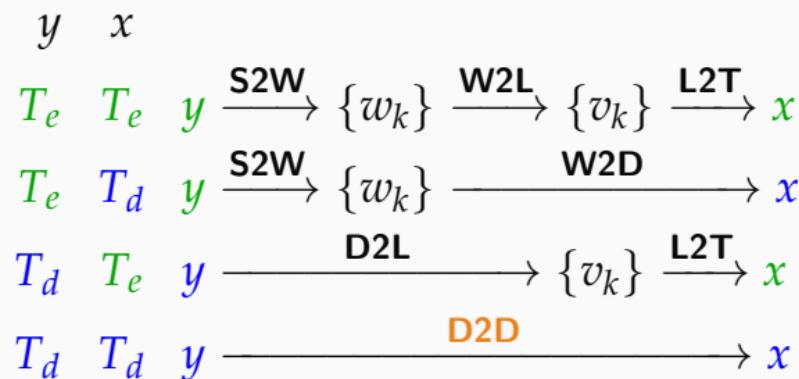
Source –  $y$

Target –  $x$

Direct tree –  $T_d$

$$F(x) = G_\delta(\|x - y\|)f(y)$$

Expand tree –  $T_e$



# DATA PARTITION

Distributed regular grid of FGT boxes

- Each box owned by an unique CPU

- Each CPU owns a sub-grid of boxes

- PETSc package

Distributed octree

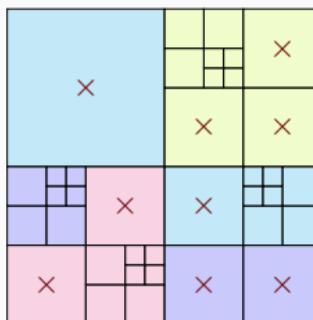
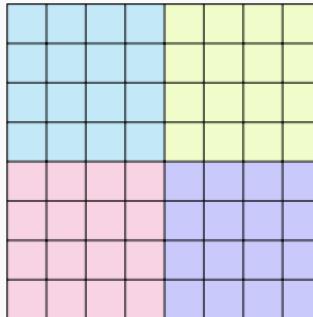
- Each leaf owned by an unique CPU

- Sorted in Morton (space-filling) order

- Direct** and Expand trees partitioned independently

- Dendro package

Distributed points – mapped to enclosing leaf

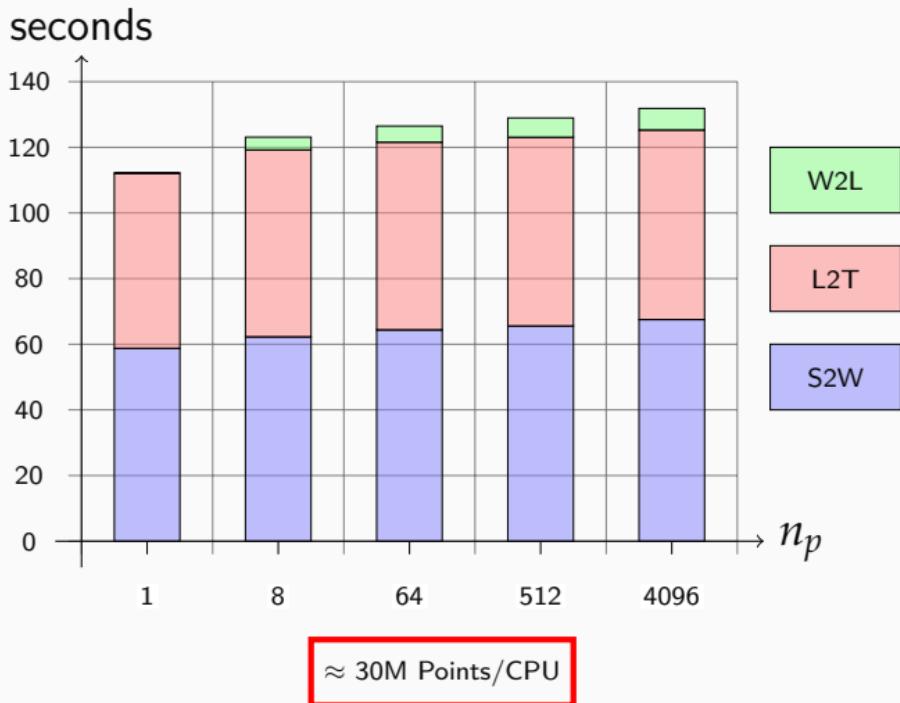


# PARALLEL ALGORITHM

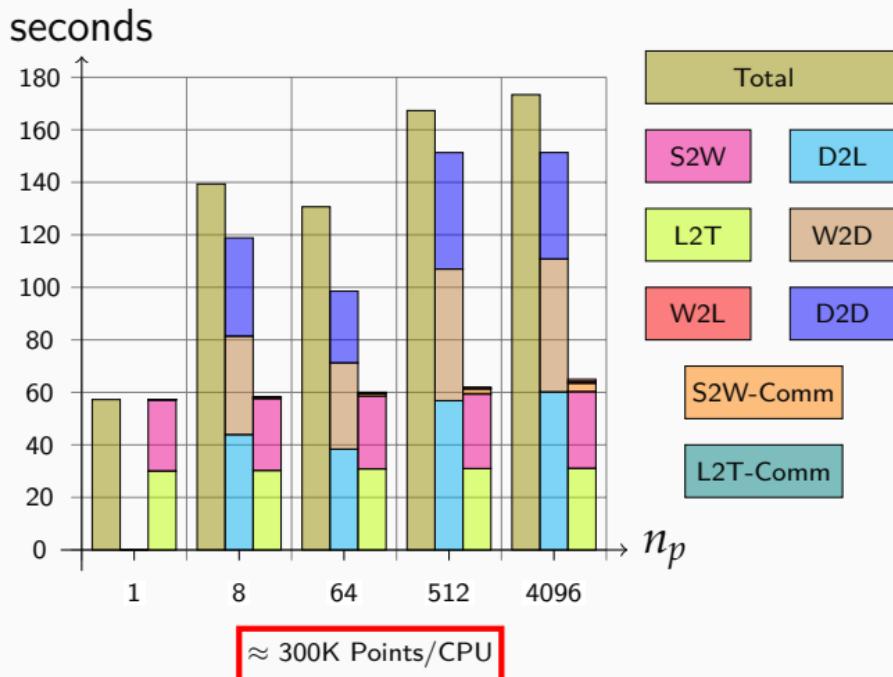
Step	Computation	Communication
S2W	Compute wave expansions for <b>Expand</b> sources	Send wave expansions to FGT boxes
W2D	Update transform at <b>Direct</b> targets	Send wave expansions to <b>Direct</b> targets
D2D	Update transform at <b>Direct</b> targets	Send <b>Direct</b> sources to <b>Direct</b> targets
W2L	Execute translation/sweeping algorithm	Communicate wave expansions of <i>ghost</i> FGT boxes
D2L	Update local expansions of FGT boxes using contributions from <b>Direct</b> sources	Send contributions from <b>Direct</b> sources to FGT boxes
L2T	Compute transform at <b>Expand</b> targets	Send local expansions to <b>Expand</b> targets

# RESULTS

# ISOGRANULAR SCALABILITY - UNIFORM



# ISOGRANULAR SCALABILITY - GAUSSIAN



# SUMMARY

A novel translation scheme

**lower computational and storage costs**

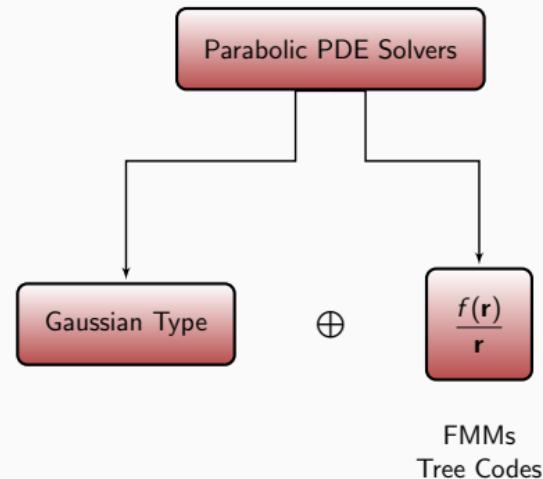
A novel octree-based algorithm for highly nonuniform distributions

**optimal in all ranges of  $\delta$**

Massively parallel algorithm for nonuniform distributions

**excellent scalability**

Supports any Gaussian-type kernel



## Reducing the constants

- Hermite to plane-wave conversion

- Overlap communication with computation

Code release under GNU -GPL [github.com/paralab/pgft](https://github.com/paralab/pgft)

Additional machinery required for *black-box* integral equation solvers for general parabolic PDEs

QUESTIONS?